

**EE 274: Data Compression,
Theory and Applications**
(Aut 22/23)

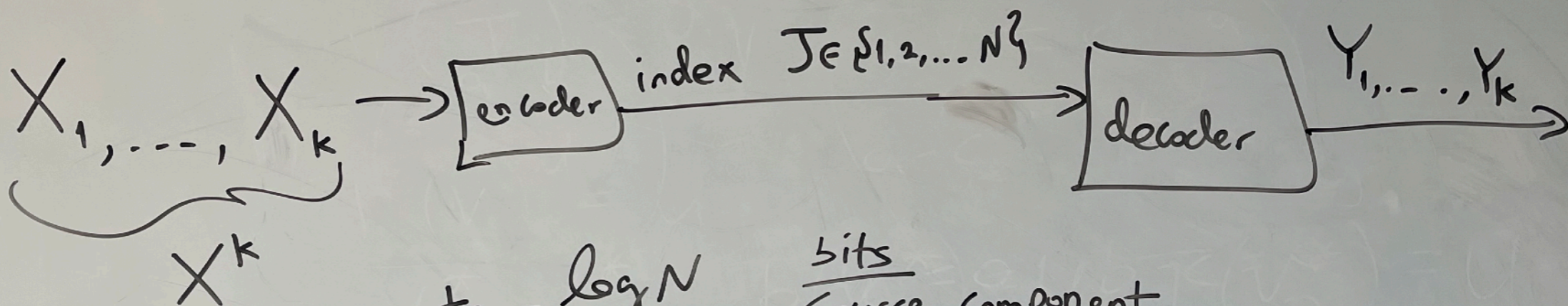


**KEEP
CALM
AND
COMPRESS
DATA**

water pouring characterization of $R(D)$ for the Gaussian source

Lossy Compression

info source:



$$\text{rate} = \frac{\log N}{k} \quad \frac{\text{bits}}{\text{Source Component}}$$

$$\text{distortion: } d(X^k, Y^k) = \frac{1}{k} \sum_{i=1}^k d(X_i, Y_i)$$

$$R(D) = \text{min rate needed to achieve }^{(\text{mean})} \text{ distortion no more than } D$$

(optimizing across k and encoders + decoders)

Suppose $\underline{X} = (X_1, X_2, \dots)$ is \forall stationary source.

Shannon's theorem for lossy compression:

$$R(D) = \lim_{k \rightarrow \infty} \min_{E d(X^k, Y^k)} \frac{1}{k} I(X^k; Y^k)$$

R(D) for a Gaussian Source: I

Denote $R_G(\sigma^2, D) \triangleq \min_{E[(X-Y)^2] \leq D} I(X; Y)$, when $X \sim \mathcal{N}(0, \sigma^2)$.

For $\vec{\sigma}^2 = \begin{pmatrix} \sigma_1^2 \\ \vdots \\ \sigma_n^2 \end{pmatrix}$ denote $R_G(\vec{\sigma}^2, D) \triangleq \min_{E[\|X^n - Y^n\|^2] \leq D} \frac{1}{n} I(X^n; Y^n)$,

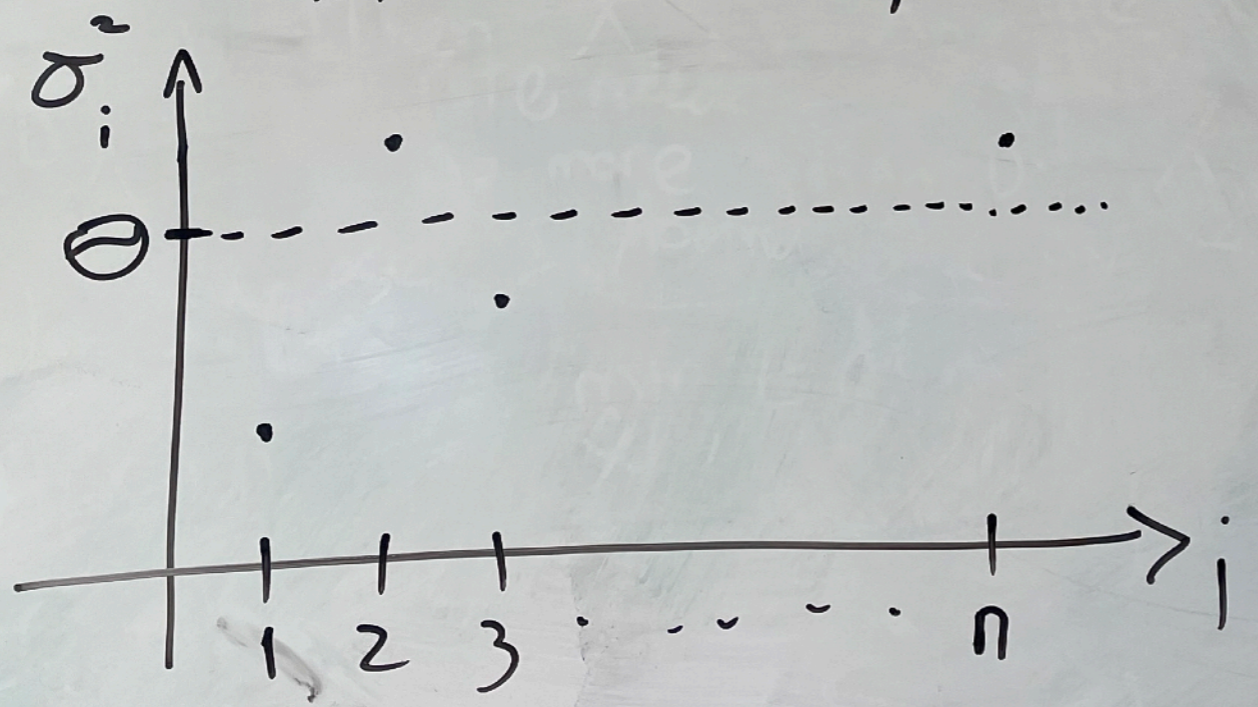
when X_1, \dots, X_n are independent with $X_i \sim \mathcal{N}(0, \sigma_i^2)$.

R(D) For a Gaussian Source: II

Recall: $R_G(\vec{\sigma}^2, D) = \min \frac{1}{n} \sum_{i=1}^n \left[\frac{1}{2} \log \frac{\sigma_i^2}{D_i} \right]_+$
 s.t. $\frac{1}{n} \sum_{i=1}^n D_i \leq D$

and is given parametrically by the curve:

$$D_\theta = \frac{1}{n} \sum_{i=1}^n \min\{\theta, \sigma_i^2\}, \quad R_\theta = \frac{1}{n} \sum_{i=1}^n \left[\frac{1}{2} \log \frac{\sigma_i^2}{\theta} \right]_+ \quad (\theta > 0)$$



R(D) For a Gaussian Source: III

X^n Gaussian with covariance Φ_{X^n}

Then $R(X^n, D)$ (under squared error)
is given by $R_G(\vec{\lambda}, D)$ where

$\vec{\lambda} = \begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{pmatrix}$ are the eigenvalues of Φ_{X^n}

R(D) For a Gaussian Source: IV

When X^n are the first n components of a Stationary Gaussian process X with covariance matrix $\Phi_n = \left\{ \phi_{|i-j|} \right\}_{\substack{1 \leq i \leq n \\ 1 \leq j \leq n}}$ where $\phi_k = \text{Cov}(X_i, X_{i-k})$

$$R(X^n, D) = R_G(\vec{\lambda}^{(n)}, D)$$

where $\vec{\lambda}^{(n)}$ is the vector of eigenvalues of Φ_n

R(D) For a Gaussian Source: V

Theorem (Toeplitz distribution):

Let $S(\omega) \triangleq \sum_{k=-\infty}^{\infty} \phi_k e^{-j\omega k}$ be the spectral density of X and $G(\cdot)$ a continuous function.

Then
$$\frac{1}{n} \sum_{i=1}^n G(\lambda_i^{(n)}) \xrightarrow{n \rightarrow \infty} \frac{1}{2\pi} \int_{-\pi}^{\pi} G(S(\omega)) d\omega$$

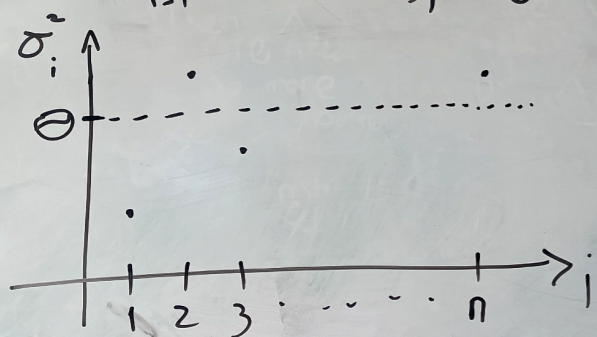
recap

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R(D) for a Gaussian Source: VI

Specializing to $G(\lambda) = \min\{\theta, \lambda^2\}$ and to $G(\lambda) = \left[\frac{1}{2} \log \frac{\lambda^2}{\theta}\right]_+$ we get:

The rate distortion function of a stationary Gaussian process with spectral density $S(\omega)$ is given parametrically by:

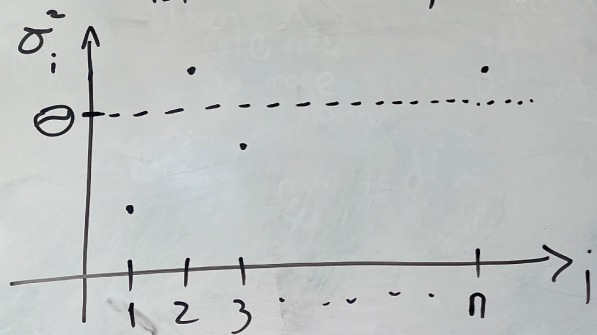
$$D_\theta = \frac{1}{2\pi} \int_{-\pi}^{\pi} \min\{\theta, S(\omega)\} d\omega, \quad R_\theta = \frac{1}{4\pi} \int_{-\pi}^{\pi} \left[\log \frac{S(\omega)}{\theta} \right]_+ d\omega$$

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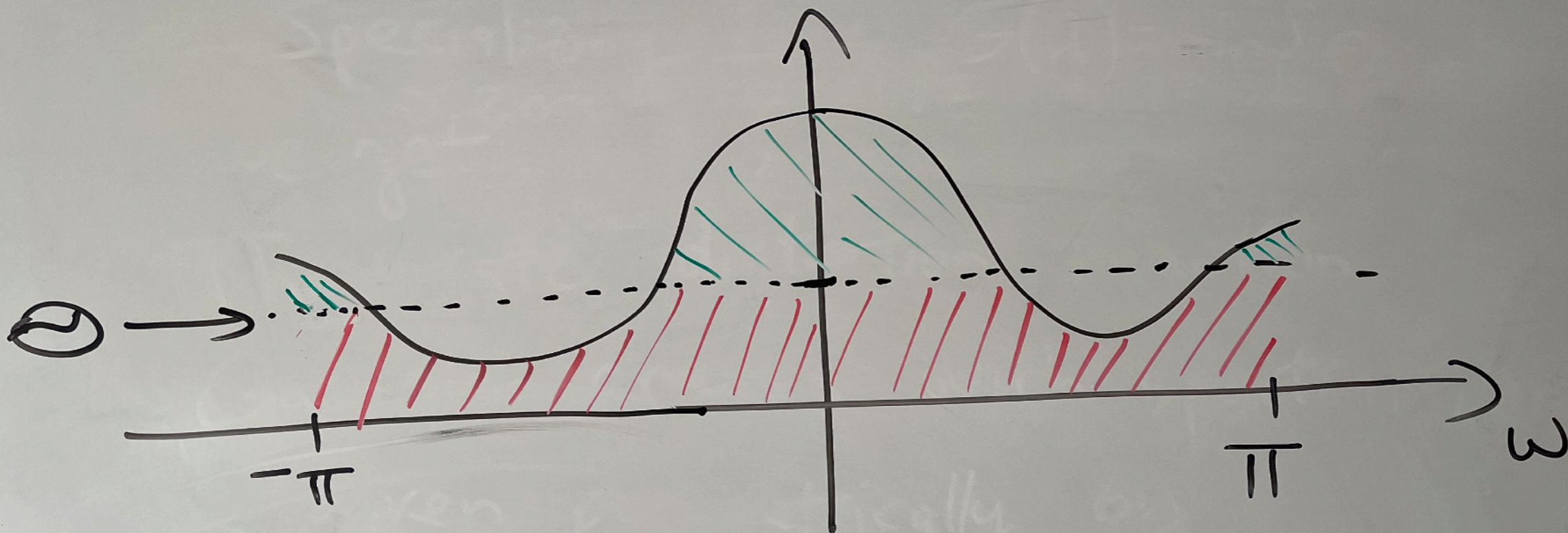
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R(D) For a Gaussian Source: VI



$D_\theta = \text{Area (//)}$

$R_\theta = \text{Area in log scale (///)}$

R(D) For a Gaussian Source: VI

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R(D) For a Gaussian Source: VIII

For $D \leq \min_{\omega} S(\omega)$ can verify that

$$R(D) = \left[\frac{1}{2} \log \frac{\sigma^2}{D} \right]_+$$

where σ^2 is the variance of the innovations of X

("kind-of" justification/inspiration for predictive coding)