

### Lecture 11

### **Lossy Compression Basics and Quantization**

### Announcements

<b>Unmatched Literals</b>	Match Length	Match Offset
AABBB	4	1
_	5	9
CDCD	2	2

1. What is the output string after decoding the first row? Ans: AABBBBBBB

- 2. What is the output string after decoding the second row? Ans: AABBB
- 3. What is the output string after decoding the third row? Ans: CDCDCD

<b>Unmatched Literals</b>	Match Length	Match Offset
ТА	1	X1
W	X2	3
-	2	2
X3	-	-

- 1. What is match offset X1 ? Ans: 2
- 2. What is match length X2 ? Ans: 1
- 3. What are the unmatched literals X3 ? Ans: DI

Consider an English text. Also consider a reversibly transformed version where each byte is replaced with itself plus one. So A becomes B, B becomes C and so on.

- Zstd would perform similarly on both the original text and the transformed version.
  () True
  - () False
- A LLM-based compressor trained on English would perform similarly on both the original text and the transformed version.

() True

() False

Your company produces a lot of data of a particular kind, and you are asked to find ways to efficiently compress it to save on bandwidth and storage costs. Which of these is a good approach to go about this?

() Use CMIX since your company deserves the best possible compression irrespective of the compute costs.

() Use gzip because LZ77 is a universal algorithm and so it has to be the best compressor for every occasion.

() Make a statistically accurate model of your data, design a predictor, and then use a context-based arithmetic coder.

() Understand the application requirements, try existing compressors like zstd and then evaluate whether there are benefits to create a domain specific compressor based on an approximate model for the data.

## Recap

So far learnt about lossless compression and tradeoffs for various *entropy coders* 

- Learnt about fundamental limits on lossless compression: H(p)
- Thumb rule:  $L(x) \propto \lceil log_2(1/p(x)) 
  ceil$
- Learn about various lossless compressors aka *entropy coders* and their implementations
  - Block codes: Shannon coding and Huffman coding
  - Streaming codes: Arithmetic coding and Asymmetric Numeral Systems
  - Universal (pattern) matching codes: LZ77
- Learnt about how to deal with non-IID sources
  - Context-based coding
  - Adaptive coding

# **Lossy Compression Basics**

Second-half of the course will look into lossy compression

- Lossless compression is a special case of lossy compression
- Everything we learnt about lossless compression is applicable to lossy compression, and in-fact, all lossy compressors deploy entropy coding as a final step
   we will learn more about this in the coming lectures
- Lossless compression assumed discrete sources but in practice we deal with continuous sources – sensors, images, audio, video, etc.

Quiz-1: How much information does a continuous source X contain?

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#### Quiz-1: How much information does a continuous source X contain?

*Ans:* Infinite! Fact about real numbers: they are uncountable, i.e., there are infinite real numbers between any two real numbers.

# **Lossy Compression Basics**

So we **cannot** represent a continuous source exactly. We need to approximate it. Approximation imply *loss* of information.

• Distortion (D) is a measure of loss of information, e.g.

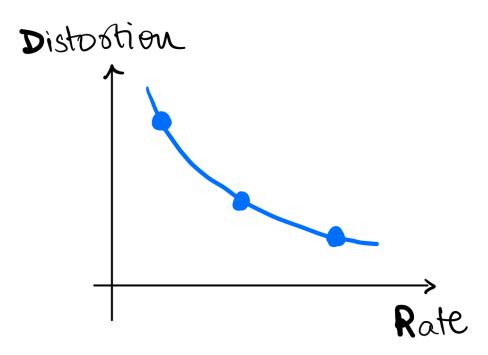
$$\circ\;$$
 MSE:  $D=\mathbb{E}[(X-\hat{X})^2]$ , MAE:  $D=\mathbb{E}[|X-\hat{X}|]$ , etc.

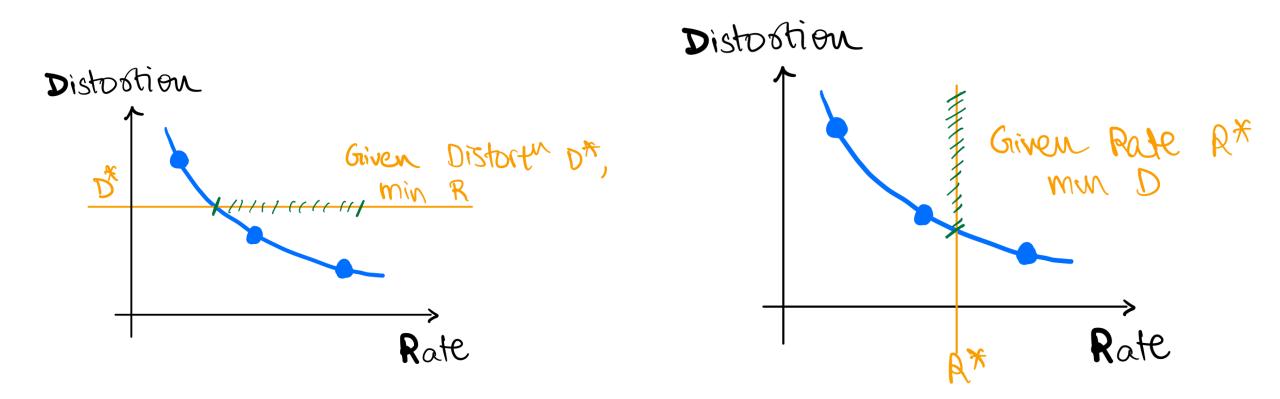
Also, this means we have a choice on how much information we want or are OK to lose.

- Rate (R) is the number of bits used to represent the source
- Higher rate, imply we should be to represent the source more accurately, i.e., lower distortion

#### This is the fundamental rate-distortion tradeoff in lossy compression.

### **Rate-Distortion Tradeoff or RD curve**





Example 1

- Let's say you are measuring temperature (T) in a room, say in Celsius, at an hourly interval.
  - Remember, physical T is a continuous source.
- Say your sensor is very sensitive and it records T = [38.110001, 36.150901, 37.122020, 37.110862, 35.827111]

Quiz-2: How many bits do we want to represent T?

#### Example 1

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#### Quiz-2: How many bits do we want to represent using T?

*Ans:* Depends on the application! If we are using it to control the AC, we might need more bits than if we are using it to decide whether to wear hoodie or T-shirt. In either case,

- we need to decide on the *distortion* we are OK with
- we can agree these many decimals are waste of bits

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Quiz-3: What are some reasonable values to encode?

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#### Quiz-3: What are the reasonable values to encode?

Ans: We can decide to round T to the nearest integer, i.e., T\_lossy = [38, 36, 37,

37, 35]. This is similar to converting T to int from float.

## Quantization

- What we did in the previous example is called *quantization*.
  - Quantization is the process of mapping a continuous source to a discrete source.
- Quantization is a lossy process, i.e., it introduces distortion.
- Quantization is a fundamental operation in lossy compression!
- Quantized values are also sometimes called *symbols* or *codewords*, and the set of available quantized values is called *codebook* or *dictionary*.
  - In previous example, codebook is {35, 36, 37, 38} and codewords for each symbol are {35, 36, 37, 37, 35}.

Quiz-4: For a codebook of size N, what is the rate R?

# Quantization

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  - In previous example, codebook is {35, 36, 37, 38} and codewords for each symbol are {35, 36, 37, 37, 35}.

#### Quiz-4: For a codebook of size N, what is the rate R?

Ans:  $R = \log_2(N)$ . Alternatively, we can say the quantized value for each symbol can take  $2^R$  unique values.

Example 2

- Now say, X is a Gaussian source with mean 0 and variance 1, i.e.,  $X \sim \mathcal{N}(0,1)$
- Say we want to represent X using just 1 bit per symbol.

Quiz-5: What are some reasonable values to encode?

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#### Quiz-5: What are some reasonable values to encode?

Ans: We can decide to convey just the sign of X, i.e.,  $\hat{X} = \mathrm{sign}(X)$  as the distribution is symmetric around 0.

#### Example 2

- Now say, X is a Gaussian source with mean 0 and variance 1, i.e.,  $X \sim \mathcal{N}(0,1)$
- Say we want to represent X using just 1 bit per symbol.
- Encode  $\hat{X}$  using the sign of X, i.e.,  $\hat{X} = \mathrm{sign}(X)$
- Say we get a positive value for  $\hat{X}$ , what should be the *quantized value* of the recovered symbol?
  - Need to decide on the *distortion* we are OK with, say MSE distortion

Quiz-6: What should be the codebook?

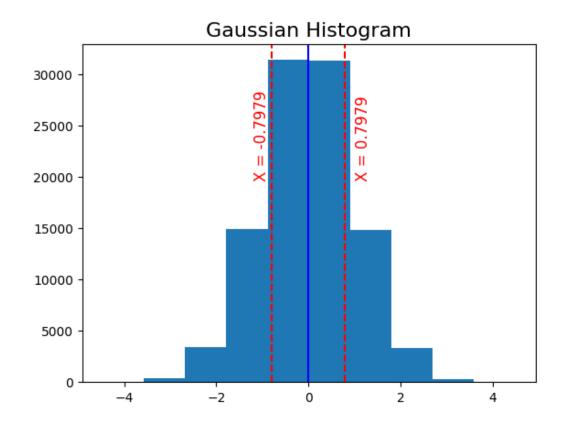
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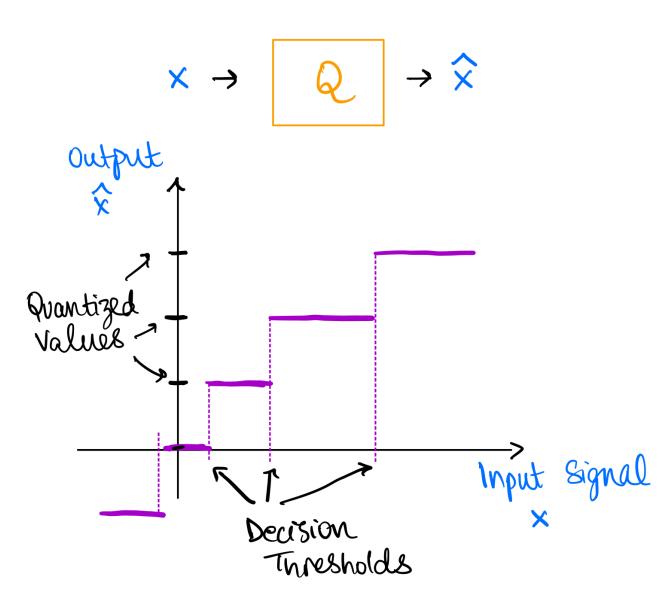
Ans: Codebook 
$$\mathscr{C} = \left\{ \mathbb{E}[(X|\hat{X} > 0)], \mathbb{E}[(X|\hat{X} < 0)] \right\}.$$
  
For gaussian, this is  $\mathscr{C} = \left\{ \sqrt{\frac{2}{\pi}}, -\sqrt{\frac{2}{\pi}} \right\}.$ 

EE 274: Data Compression - Lecture 11



# **Scalar Quantization**

- This is an example of scalar quantization.
- We are quantizing each symbol independently. But can we do better?



- Maybe we can work with two (or more) symbols at a time?
- Say we have  $X = [X_1, X_2]$ , where  $X_1, X_2 \sim \mathcal{N}(0, 1)$ 
  - $\circ\,$  you can also think of it as you generated  $\,$  2\*N  $\,$  samples from  $\mathcal{N}(0,1)$  and then split them into two groups of size  $\,$ N  $\,$  (similar to  $\,$ block codes  $\,$ in lossless compression)  $\,$
  - $\circ~$  or you can think of it as you have two sensors measuring the same source
  - or you can think of it as having two sensors measuring two different sources

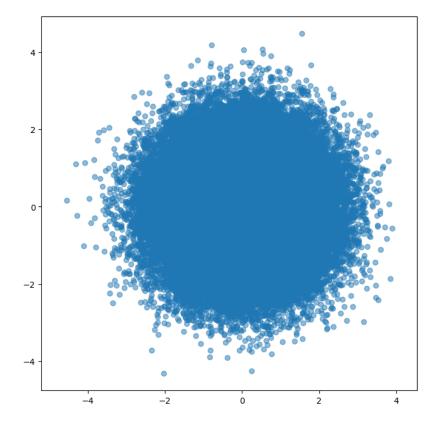
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Quiz-7: I want to compare it with 1 bit/symbol scalar quantization. What's the size of codebook allowed?

Ans:  $2^{1 \text{ bit/symbol} \times 2 \text{ symbol/code-vector}} = 4$ . Generalizing, we can have codebook of size  $N = 2^{R*k}$  for vectors (blocks) of size k and R bits/symbol.

We can have codebook of size  $N=2^{R*K}$  for vectors (blocks) of size k and R bits/symbol. In other words,  $R=(\log_2 N)/k$  bits/symbol.



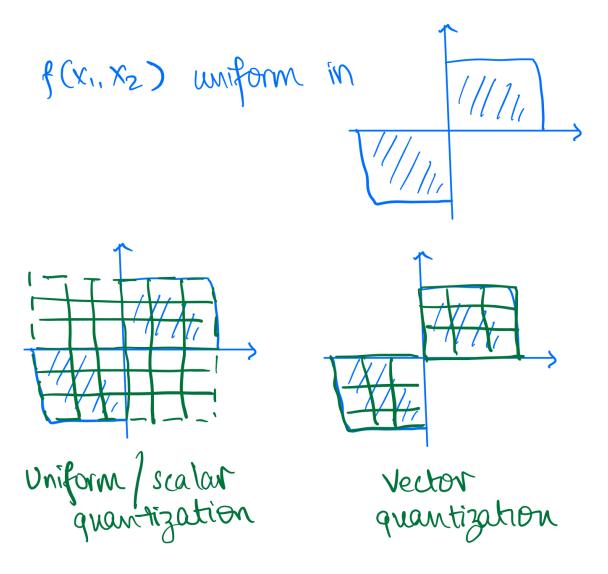
### **Vector Quantization (formally)**

- A quantizer is a mapping  $Q: \mathbb{R}^k \to \mathscr{C}$  where  $\mathscr{C} = \left\{ \underline{y}_i \right\}_{i=1}^N$  is the "codebook" or "dictionary" comprising of N k-dimensional vectors.
- The mapping is defined by:  $Q(\underline{x}) = \underline{y}_i$  if  $\underline{x} \in S_i$  where  $\{S_i\}_{i=1}^N$  is a partition of  $\mathbb{R}^k$  $\bigcup_{i=1}^N S_i = \mathbb{R}^k; \quad S_l \cap S_m = \phi, l \neq m.$
- The rate is  $R = rac{\log N}{k} rac{ ext{bits}}{ ext{sample}}; N = 2^{kR}$
- Let's map this to the examples we looked at.

Benefits:

- We can exploit dependence between vector components
- We can have more general decision regions (than could be obtained via Scalar Quantization)

# **Vector Quantization Example**



Some comments (without proofs):

- Optimal regions are generally not uniform (as in scalar quantization) even in simple uniform IID case!
- In the 2D case of uniform IID, a hexagonal lattice provides most optimal regions with respect to MSE distortion.
  - This is called *lattice quantization* or *Voronoi diagram* and can accommodate more than 2 dimensions.
  - $\circ \; rac{MSE_{lattice}}{MSE_{SQ}} pprox 0.962$  for 2D case.

Abstract—The quantization of *n*-dimensional vectors in  $\mathbb{R}^n$  with an arbitrary probability measure, under a mean-square error constraint, is discussed. It is demonstrated that a uniform, one-dimensional quantizer followed by a noiseless digital variable-rate encoder ("entropy encoding") can yield a rate that is, for any *n*, no more than 0.754 bit-per-sample higher than the rate associated with the optimal *n*-dimensional quantizer, regardless of the probabilistic characterization of the input *n*-vector for the allowable mean-square error.

- Vector quantization can be a lot of hard work with little gain. Be careful of the tradeoff between complexity and gain.
- Abstract from: On universal quantization, Ziv

# **Vector Quantization -- Practical Considerations**

• In general, optimal regions are not easy to compute, and we need to resort to iterative algorithms.

Quiz-8: Have you seen this problem before in some other context?

# **K-means Algorithm**

- It's same as K-means clustering algorithm in ML! Also called as *Lloyd-Max* algorithm or *Generalized Lloyd* algorithm.
  - You want to cluster data points into N clusters corresponding to codebook (k in k-means) such that the average distortion is minimized.
- Historical Note:
  - First proposed by Stuart Lloyd in 1957 (motivated by audio compression) at Bell Labs
  - Was widely circulated but formally published only in 1982
  - Independently developed and published by Joel Max in 1960, therefore sometimes referred to as the Lloyd-Max algorithm
  - Generalized Lloyd specialized to squared error is the Kmeans clustering algorithm widely used in Machine Learning

### **K-means Algorithm**

- Given some data points, we can compute the optimal codebook and the corresponding partition of the data points.
- Main idea is to do each-step iteratively:
  - Given a codebook, compute the best partition of the data points
  - Given a partition of the data points, compute the optimal codebook
  - Repeat until convergence

```
K-means Algorithm
```

```
def k_means(data, k, max_iterations=100):
    centroids = initialize_centroids(data, k) # some random initialization for centroids (codebook)
    for iteration in range(max_iterations): # some convergence criteria
        # Assign data points to the nearest centroid -- this is the partition step
        clusters = assign_data_to_centroids(data, centroids)
        # Calculate new centroids -- this is the codebook update step
        new_centroids = calculate_new_centroids(data, clusters)
        if np.allclose(centroids, new_centroids): # some convergence criteria
            break
        centroids = new_centroids # update centroids
    return clusters, centroids
```

Note: k is the size of the codebook (referred to as N in the rest of lecture) and data is the set of data points.

# **K-means Algorithm**

```
def k means(data, k, max iterations=100):
    centroids = initialize centroids(data, k) # some random initialization for centroids (codebook)
    for iteration in range(max iterations): # some convergence criteria
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        clusters = assign data to centroids(data, centroids)
       # Calculate new centroids -- this is the codebook update step
        new centroids = calculate new centroids(data, clusters)
        if np.allclose(centroids, new centroids): # some convergence criteria
            break
        centroids = new centroids # update centroids
    return clusters, centroids
def initialize centroids(data, k):
   # Randomly select k data points as initial centroids
    return data[np.random.choice(len(data), k, replace=False)]
def assign data to centroids(data, centroids):
   # Assign each data point to the nearest centroid
    distances = np.linalg.norm(data[:, np.newaxis] - centroids, axis=2)
    clusters = np.argmin(distances, axis=1)
    return clusters
def calculate new centroids(data, clusters):
   # Calculate new centroids as the mean of data points in each cluster
    new centroids = np.array([data[clusters == i].mean(axis=0) for i in range(len(np.unique(clusters)))])
    return new centroids
```

## **Example Notebook**

https://colab.research.google.com/drive/16dYjBEc499HgHoZRxcyeg0YmNAb5AwAW? usp=sharing

### **More resources**

We only scratched the surface of quantization. Many more advanced topics:

- Constrained vector quantization
- Predictive vector quantization
- Trellis coded quantization
- Generalized Lloyd algorithm
- ...

For more details, see:

- Fundamentals of Quantization: Gray
- Vector Quantization and Signal Compression: Gersho, Gray

### Next time

We will look into the question of what is the fundamental limit on lossy compression, i.e. what is the best possible rate-distortion tradeoff.